

Cross Flow Effects on Glaze Ice Roughness Formation

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Cross Flow Effects on Glaze Ice Roughness Formation

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Abstract

The present study examines the impact of large—scale cross flow on the creation of ice roughness elements on the leading edge of a swept wing under glaze icing conditions. A three—dimensional triple—deck structure is developed to describe the local interaction of a 3D air boundary layer with ice sheets and liquid films. A linear stability analysis is presented here. It is found that, as the sweep angle increases, the local icing instabilities enhance and the most linearly unstable modes are strictly three dimensional.

Nomenclature

bulk freezing temperature, 273°K for water

 T_{m}

* III	outh freezing temperature, 270 ft for water
γ_{sl}	solid-liquid surface tension
$\gamma_{l\nu}$	liquid-vapor surface tension
H_{sl}	latent heat of freezing per unit mass of ice
$H_{l\nu}$	latent heat of evaporation per unit mass of water
6	density
c_p	specific heat
k	thermal conductivity
α	thermal diffusivity
μ	dynamic viscosity
θ_{m}	density ratio, = $1 - (\varrho_l/\varrho_s)$
LWC	liquid water content of impinging droplets
$\beta(s)$	local collection efficiency
κ	sum of the principal curvatures of the interface
U_{∞}	ambient airspeed
T_{∞}	ambient air temperature and airspeed
P_{∞}	ambient air pressure
L_{ref}	characteristic length scale
ΔT	freestream supercooling, = $T_m - T_{\infty}$
${ m M}_{\infty}$	freestream Mach number
Pr	Prandtl number of air, = 0.72
Re	freestream Reynolds number, = $\varrho_{\infty}U_{\infty}L/\mu_{\infty}$
Ste	Stefan number, = $c_{p,s} \Delta T/H_{sl}$
Sc	Schmidt number, = μ/QD_{AB}
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(s,N) boundary layer scaled coordinates (u,v)_B boundary layer scaled velocity components (p,T)_B boundary layer scaled pressure / temperature $h_0(s,t)$ boundary layer scaled water film thickness $\delta_0(s,t)$ boundary layer scaled ice sheet thickness (X,Y) local triple deck scaled coordinates (U,V) triple deck scaled velocity components (P,T) triple deck scaled pressure / temperature h(X,t) triple deck scaled water film thickness $\delta(X,t)$ triple deck scaled ice sheet thickness scaled impingement velocity Vimp boundary layer scaled wall layer thickness δ_{wall} scaled steady state inner wall temperature $T_{w.s}$ dimensionless global time t_0 dimensionless local triple deck time t d roughness element diameter R airfoil leading-edge nose radius accumulation parameter, dimensionless $A_{\rm c}$ freezing fraction, dimensionless Subscripts

(U,T)_e inviscid surface velocity / temperature

 ∞ in the freestream air l in the liquid water region s in the frozen ice layer

w in the airfoil surface metal wall region

Superscript

* dimensional quantity

Introduction

This work analyzes the linear stability of a three–dimensional laminar boundary layer flowing past a thin layer of surface water, formed and replenished from the impingement of small supercooled droplets, on a growing glaze ice substrate near the leading edge of a wing surface with the presence of significant cross flow. Specifically flow over a swept wing is considered, as shown in Fig. 1. Recent experimental investigations on glaze ice shape formation on swept wings 1–4have shown that the sweep of a wing can affect the glaze ice accretion process. Figures 2 and 3 are front–view images of a portion of the wing leading edge after approximately 1 minute of ice accretion under similar icing conditions,

mass diffusivity coefficient

viscosity ratio of water to air

saturated vapor pressure of pure water

relative molecular mass

 D_{AB}

M

 \mathcal{M}

 P_{v}

with n=0.41 and 0.43 respectively. Clearly the induced cross flow on swept wings has changed and modified the surface water run—back behavior, relative to the zero sweep configuration, and consequently the glaze ice accretion process is changed as well. One of the most noticable difference between Figs. 2 and 3 is the replacement of a smooth zone (i.e. 2D dominant modes with diminishing growth rate) with well defined 3D roughness field along the attachment line (or the stagnation line) region when the wing is swept.

In a previous study on the formation of ice roughness on a NACA 0012 airfoil leading edge under glaze icing conditions, Tsao & Rothmayer⁵ showed that a mutual interaction between the film dynamics and the ice accretion process can lead to the creation of surface ice roughness elements. The linear stability analysis has predicted that the most unstable and fastest growing modes have streamwise wavelength of millimeter size, and also there is a narrow region of strong instability centered at some distance downstream of the nose. Although qualitative features of glaze ice roughness formation on an airfoil leading edge observed experimentally^{6–7} are well captured by the 2D model, its usefulness in helping one to understand the aforementioned change in roughness formation mechanism associated with swept wings is then limited because the flow is 3D, even if only weakly so. Therefore, a fully three-dimensional triple-deck model is used to study the effect of cross flow on local icing instabilities leading to the formation of glaze ice rough-

The second area of interest of the paper concerns the possible connection between the Messinger freezing fraction and the icing instability. The Messinger model in its original form represents an equilibrium energy balance, in which the freezing fraction indicates how much super-cooled water droplets upon impact will turn into ice mass in the equilibrium steady state. Its numerical value, ranging from 0 to 1, determine the physical appearance of the accreted ice. But why does this parameter have such a morphological feature? Is it related to the dynamic aspect of the icing process? As a starting effort, a theoretical derivation of the freezing fraction expression within the context of the current model is made, and it is found that the freezing fraction is directly tied to the samll scale icing instability. A brief discussion of its implication will be given.

The Nonlinear 3D Triple-Deck Flow

Tsao & Rothmayer in Ref. 5 have laid out a complete derivation of the overall asymptotic structures for a 2D airfoil glaze icing problem, which includes global boundar—layer and local triple—deck scaled structures. As for the 3D counterpart problem, i.e. flow over a swept wing, the asymptotic scaling analysis given in Ref. 5 can be readily applied. Unfortunately, space does not permit a full discussion and so the paper will focus only on the local flow structures which are important to the glaze ice roughness formation process.

In describing the local flow, a Cartesian coordinate system (x,y,z) and their corresponding velocities (u,v,w) are taken to be centered at some point on the wing surface, see Fig. 1. The local near-wall streamline (for $y\rightarrow 0$) defines the streamwise direction, x, to which the crossflow direction, z is normal, and y denotes the coordinate which is perpendicular to and out of the wing surface. Notice that the angle between the local streamwise direction and the global chordwise direction is the flow angle θ , where

$$\theta = \tan^{-1} (U_s/U_c).$$

Here the subscripts c and s indicate the chordwise and spanwise directions respectively. Also, it should be noted that the present analysis neglects possible surface curvature effects, which is generally acceptable in the *thin layer* model considered here but may fail in other situations.

As shown in Fig. 4, the local air flow is a steady three–dimensional tripl–deck structure. The basic equations and boundary conditions governing the local 3D triple–deck flow is similar to the 2D case derived in Ref. 5 (i.e. the problem in the z–direction is essentially a mirror image of the problem in the x–direction provided finite boundary–layer scaled wall shear stressess and edge velocities) and will simply be stated here. Interested readers are referred to that study, and some related detailsof 3D boundary layer instability problem may be found in Stewart & Smith⁸ and Ryzhov & Terent'ev⁹.

Let us further confine ourselves to the lower near—wall viscous sublayer (*lower–deck*) where the air flow can affect the growth dynamics of the water

film and ice layer. The governing equations for the local triple-deck structure are given in Prandtl transposed variables by

$$U_X + V_Y + W_Z = 0,$$
 (1)

$$UU_X + VU_Y + WU_Z = -P_X + U_{YY}, \quad (2)$$

$$UW_X + VW_Y + WW_Z = -P_Z + W_{YY},$$
 (3)

$$UT_X + VT_Y + WT_Z = Pr^{-1}T_{YY}$$
 (4)

with the boundary conditions

$$U(X, 0, Z) = V(X, 0, Z) = W(X, 0, Z) = 0,$$
 (5)

$$T(X, 0, Z) = \left[\frac{k_{\infty}}{k_{l}}(T_{Y}(X, 0, Z) - \tilde{E}) + \tilde{H}v_{imp}\right] \times (h(X, Z, t) - \delta(X, Z, t)) + \Gamma(\delta_{XX} + \delta_{ZZ})$$
(6)

and the farfield matching conditions

$$\begin{split} \mathbf{U} & \to \lambda_{\mathbf{X}} \left(\mathbf{Y} + \mathbf{h} - \mathbf{h}_0 + \mathbf{A}(\mathbf{X}, \mathbf{Z}) \right) \quad \text{as} \quad \mathbf{Y} \to \infty, \\ \mathbf{W} & \to \lambda_{\mathbf{Z}} \left(\mathbf{Y} + \mathbf{h} - \mathbf{h}_0 + \mathbf{A}(\mathbf{X}, \mathbf{Z}) \right) \quad \text{as} \quad \mathbf{Y} \to \infty, \\ \mathbf{T} & \to \mathbf{q} \left[\mathbf{Y} + \mathbf{h} - \mathbf{h}_0 + \mathbf{A}(\mathbf{X}, \mathbf{Z}) \right. \\ & \left. + \frac{\mathbf{k}_{\infty}}{\mathbf{k}_l} \Theta \left(\mathbf{h}_0 - \delta_0 \right) \right], \quad \text{as} \quad \mathbf{Y} \to \infty \end{split}$$

where λ_X and λ_Z denote the local boundary layer wall shears, q is the local boundary layer surface heat transfer, (h_0 , δ_0) represent the boundary layer scaled water film and ice sheet thickness and

$$\Theta = 1 + \frac{k_l H_0 v_{imp,0}}{k_{\infty} q} - \frac{\tilde{E}}{q},$$

$$\tilde{E} = Re^{-1/2} \frac{H_{l\nu} m_{evap}^* L_{ref}}{k_{\infty} \Delta T},$$

$$m_{evap}^* = \frac{h_c}{c_{p,\infty}} \left(\frac{Pr}{Sc}\right)^{\frac{2}{3}} \left(\frac{M_w}{M_a}\right) \left[\frac{P_{v,s} - H_r(\frac{P_e^*}{P_w^*})P_{v,\infty}}{P_e^*}\right],$$

$$\tilde{H}_0 = Re^{-2/8} \mathcal{M}e^{-1} Pr\left(\frac{\rho_l k_{\infty}}{\rho_{\infty} k_l}\right) \left[\frac{U_{\infty}^2}{2c_{p,\infty} \Delta T} - \frac{c_{p,l}}{c_{p,\infty}}\right],$$

$$(v_{imp}, v_{evap})_0 = Re^{6/8} \mathcal{M}e\left(\frac{LWC}{\rho_l} \beta, \frac{m_{evap}^*}{\rho_l U_{\infty}}\right),$$

$$\tilde{H} = Re^{1/8} \mathcal{M}e^{-1} Pr\left(\frac{\rho_l k_{\infty}}{\rho_{\infty} k_l}\right) \left[\frac{U_{\infty}^2}{2c_{p,\infty} \Delta T} - \frac{c_{p,l}}{c_{p,\infty}}\right],$$

The viscosity ratio of water to air, \mathcal{M} , is assumed to be large so that the lubrication approximation can be used to describe the film flow.

 $(v_{imp}, v_{evap}) = Re^{3/8} \mathcal{M}_{0} \left(\frac{LWC}{\rho_{I}} \beta, \frac{m_{evap}^{*}}{0.11} \right).$

The unknown displacement function, A(X,Z), is related to the self–induced air pressure through the Cauchy–Hilbert integral:

$$P(X,Z) = \frac{-1}{2\pi} \int_{-\infty}^{\infty} \frac{(U_e \partial/\partial \xi + W_e \partial/\partial \eta)^2 d\xi d\eta}{[(X - \xi)^2 + (Z - \eta)^2]^{1/2}}. (10)$$

The U_e and W_e stand for the velocities just outside the boundary layer. The Gibbs-Thomson parameter Γ , shown in eqn. (22), comes from the Gibbs-Thomson relation and is defined as

$$\Gamma \equiv \frac{\gamma_{sl} T_m Re^{1/4}}{\rho_s H_{sl} \Delta T L_{ref}} = \frac{d_0}{L_{ref}}$$
(11)

where d₀ is a capillary length defined by

$$d_0 \equiv \frac{\gamma_{sl} T_m Re^{1/4}}{\rho_s H_{sl} \Delta T}.$$
 (12)

The local water film motion and ice layer growth are nonlinearly coupled and governed by

$$\begin{split} \overline{h}_{t} + \frac{\partial}{\partial X} & \left[U_{Y}(X, 0, Z) \frac{\tilde{h}^{2}}{2} - (\tilde{P}_{X} + \tilde{G}_{X} \sin \theta_{X}) \frac{\tilde{h}^{3}}{3} \right] \\ & + \frac{\partial}{\partial Z} \left[W_{Y}(X, 0, Z) \frac{\tilde{h}^{2}}{2} - (\tilde{P}_{Z} + \tilde{G}_{Z} \sin \theta_{Z}) \frac{\tilde{h}^{3}}{3} \right] \\ & = v_{imp} - v_{evap} \end{split}$$

$$(13)$$

and

$$S_{1} \operatorname{Pr}\left(\frac{\alpha_{\infty}}{\alpha_{s}}\right) \frac{\partial \delta}{\partial t} = \frac{k_{w}}{k_{s}} \left(\frac{1 - T_{w,s}}{\delta_{wall}}\right) - \frac{k_{l}}{k_{s}} \left(\frac{k_{\infty}}{k_{l}} (T_{Y}(X, 0, Z) - \tilde{E}) + \tilde{H} v_{imp}\right),$$
(14)

where $\bar{h} = h - \theta_m \delta$, $\tilde{h} = h - \delta$ and $\tilde{P}_X = P_X - \tilde{T}(\Delta h)_X + \tilde{G}_Y(\cos \theta_X + \cos \theta_Z) h_X$ $\tilde{P}_Z = P_Z - \tilde{T}(\Delta h)_Z + \tilde{G}_Y(\cos \theta_X + \cos \theta_Z) h_Z$ with

$$\Delta h \equiv h_{XX} + h_{ZZ}$$
.

The gravitational and surface tension parameters of liquid water are defined as

$$(\tilde{G}_{X,Z}, \tilde{G}_Y) = (Re^{-1/8}, Re^{-3/8})(\rho_l)(\frac{gL}{U_{\infty}^2})$$

= $(Re^{-17/8}, Re^{-19/8})(\rho_l \rho_{\infty} gL^3/\mu_{\infty}^2)$

and

$$\tilde{T} = Re^{-13/8} (\rho_{\infty} \gamma_{lv} L/\mu_{\infty}^2).$$

Also in the Stefan equation, i.e. eqn. (14), the triple–deck scaled Stefan number is defined as

$$S_1 = Re^{1/8} (MSte)^{-1},$$

where

$$Ste \, \equiv \frac{c_{p,s} \, \Delta T}{H_{sl}}, \ \ Re \, \equiv \frac{\rho_{\, \infty} U_{\, \infty} L_{ref}}{\mu_{\, \infty}}. \label{eq:Ste}$$

Linear Stability Analysis

As in the studies of Smith¹⁰ and others^{5,11,12}, the flow is resolved into its primary and perturbation parts. Although we are considering only the leading order term, Smith¹⁰ shows that high order terms could be added to improve the accuracy of the solution. The variables are expanded in normal mode form as follows:

$$\begin{split} &(\mathbf{U}, \mathbf{V}, \mathbf{W}, \mathbf{P}, \hat{\mathbf{P}}, \mathbf{T}, \mathbf{A}, \mathbf{h}, \boldsymbol{\delta}) = (\lambda_{\mathbf{X}} \mathbf{Y}, 0, \lambda_{\mathbf{Z}} \mathbf{Y}, 0, 0, \\ &\mathbf{q}[\mathbf{Y} + \frac{\mathbf{k}_{\infty}}{\mathbf{k}_{l}} \Theta(\mathbf{h}_{0} - \boldsymbol{\delta}_{0})], 0, \mathbf{h}_{0}, \boldsymbol{\delta}_{0} + \boldsymbol{\epsilon}(\overline{\mathbf{U}}(\mathbf{Y}), (15) \\ &\overline{\mathbf{V}}(\mathbf{Y}), \overline{\mathbf{W}}(\mathbf{Y}), \overline{\mathbf{P}}, \overline{\overline{\mathbf{P}}}(\overline{\mathbf{y}}), \overline{\mathbf{T}}(\mathbf{Y}), \overline{\mathbf{A}}, \overline{\mathbf{h}}, \overline{\boldsymbol{\delta}}) e^{\mathbf{i} (k_{\mathbf{X}} \mathbf{X} + k_{\mathbf{Z}} \mathbf{Z}) + \omega \mathbf{t}}, \end{split}$$

where $k_{\rm X}$ and $k_{\rm Z}$ (both are real) denote the tripledeck scaled wave numbers in X and Z directions and $(l^*)_{\rm X,Z} = 2\pi/(k_{\rm x},k_{\rm Z})^* = 2\pi L_{\rm TD}/(k_{\rm x},k_{\rm Z})$ are the associated disturbance wavelengths (here $L_{\rm TD} = {\rm Re}^{-3/8}L_{\rm Tef}$). The triple-deck scaled frequency ω is complex, $\omega = \omega_r + i \, \omega_i$, and may be readily related to the well-known complex wave speed, $c = c_r + i \, c_i$, where $c = \omega/(-ik)$ with $k^2 = k_{\rm x}^2 + k_{\rm z}^2$. As usual, c_r is the phase speed of the wave, whereas c_i determines the degree of damping (if $c_i < 0$, $\omega_r < 0$), or amplification (if $c_i > 0$, $\omega_r > 0$).

The three–dimensional linear stability problem can be further reduced to an *equivalent two–dimensional problem* if one lets

$$k^{2} = k_{x}^{2} + k_{z}^{2}, \quad kU = k_{x}\overline{U} + k_{z}\overline{W},$$

$$k\lambda = k_{x}\lambda_{X} + k_{z}\lambda_{Z}, \quad kUe = k_{x}U_{e} + k_{z}W_{e}$$

$$\cos\theta = \cos\theta_{X} + \cos\theta_{Z}, \qquad (16)$$

$$kG\sin\theta = k_{x}\widetilde{G}_{X}\sin\theta_{X} + k_{z}\widetilde{G}_{Z}\sin\theta_{Z},$$

$$V = \overline{V}, \quad T = \overline{T}, \quad \text{and} \quad P = \overline{P}.$$

The ensuing quadratic dispersion relation for the linear instability eigenvalues, i.e. ω , is found to be $(\gamma \beta L_0) \omega^2 + (\Lambda \beta - \theta_m N_0 L_0 + e_1 \gamma L_0) \omega$

$$+ (\Lambda e_1 - N_0 L_0 e_2 - M_v) = 0, \tag{17}$$

where

$$\begin{split} &\Lambda = \overline{\Lambda} \left[q\Theta + \frac{k_I}{k_\infty} \Gamma k^2 \right], \ \, \gamma = -\frac{k_S \, \alpha_\infty S_1 Pr}{k_\infty \alpha_S \, \overline{\theta}}, \\ &\overline{\Lambda} = (1 - \frac{\Phi_1}{k_\infty}) \, \text{Ai}'(0) - \frac{\Phi_2}{\overline{\theta} k_\infty} \, \text{Ai}(0), \\ &\beta = \frac{e^{\, i \pi / 6} \, k^{1/3} \, |k| \, \text{Ue}^2}{3 \, \lambda^{5/3} \text{Ai}'(0)} - 1, \\ &L_0 = L_1 \, \text{Ai}(0) - L_2 \, \text{Ai}'(0), \\ &L_1 = \frac{k_I}{k_\infty} + \frac{\Phi_2}{k_\infty} (h_0 - \delta_0), \\ &L_2 = (1 - \frac{\Phi_1}{k_\infty}) \, \overline{\theta} \, (h_0 - \delta_0), \\ &N_0 = (1 - \frac{\Phi_1}{k_\infty}) N_1 - \frac{\Phi_2}{\overline{\theta} k_\infty} N_2, \\ &N_1 = a_1 \text{Ai}'(0) + Pr^{-\frac{1}{3}} (\frac{q}{\lambda}) \overline{c}_1 \text{Ai}(0) + Pr^{\frac{1}{3}} \, \overline{\alpha} \, L_j'(0) \\ &+ (\frac{q}{\lambda}) \frac{(Pr - 1)}{Pr_3^2} \, \overline{c}_1 L_k'(0), \\ &N_2 = a_1 \text{Ai}(0) + Pr^{\frac{1}{3}} \overline{\alpha} L_j'(0) + (\frac{q}{\lambda}) \frac{(Pr - 1)}{Pr_3^2} \overline{c}_1 L_k(0), \\ &\Phi_1 = (\frac{-H_{h_0}}{c_{p,\infty} \Delta T}) \left(\frac{Pr}{Sc} \right)^{\frac{2}{3}} \left(\frac{M_w}{M_a} \right) \left[\frac{Pv,s - H_r}{P_c^*} (\frac{P^*_c}{D_w^*}) Pv,\infty}{P_c^*} \right], \\ &\Phi_2 = \left(\frac{-q \, H_h}{c_{p,\infty} \Delta T} \right) \left(\frac{Pr}{Sc} \right)^{\frac{2}{3}} \left(\frac{M_w}{M_a} \right) \left[\frac{17.15 \, Pv,s \, \Delta T}{P_c^* \, (T_m - 38.25)} \right], \\ &a_1 = L_0^{-1} \left\{ q\Theta\beta + L_2 \left[\frac{qA_i(0)}{\lambda \, Pr_3^2} \overline{c}_1 + Pr^{\frac{1}{3}} L_j'(0) \, \overline{\alpha} \right. \right. \\ &\left. \frac{q(Pr - 1)L_k'(0)}{\lambda \, Pr_3^2} \overline{c}_1 \right] - L_1 \left[Pr^{\frac{1}{3}} L_j'(0) \, \overline{\alpha} \right. \\ &+ \frac{q(Pr - 1)L_k(0)}{\lambda \, Pr_3^2} \overline{c}_1 \right] \right\}, \\ &e_1 = e_3 \, \beta + \frac{1}{2} \, i k (h_0 - \delta_0)^2 \, \overline{\theta} \, A_i(0) \, \overline{c}_1 + \frac{1}{3} \, k^2 (h_0 - \delta_0)^3 \, \hat{P}, \\ &e_2 = i k \lambda (h_0 - \delta_0) - i k (h_0 - \delta_0)^2 \, G \sin \theta, \\ &e_3 = i k \lambda \, (h_0 - \delta_0) - i k (h_0 - \delta_0)^3 \, \widetilde{G}_Y \, \cos \theta \\ &- i k (h_0 - \delta_0)^2 \, G \sin \theta + \frac{1}{3} \, k^4 (h_0 - \delta_0)^3 \, \widetilde{T}, \\ &M_v = N_0 [A_m \overline{\theta} Ai'(0) + B_m Ai(0)] [q\Theta + \frac{k_I}{k_I} \Gamma k^2], \end{aligned}$$

$$A_{\scriptscriptstyle m} = \frac{-\, \, \mathcal{M}_{\scriptscriptstyle o}}{Pr\, Re^{\,1/8}} (\frac{\rho_{\scriptscriptstyle \, w}}{\rho_{\scriptscriptstyle \it l}}) \! \Big(\! \frac{Pr}{Sc} \! \Big)^{\! \frac{2}{3}} \! \Big(\frac{M_{\scriptscriptstyle \, w}}{M_{\scriptscriptstyle \it a}} \! \Big) [\frac{P_{\scriptscriptstyle \, v,s} \, - \, H_{\scriptscriptstyle \, r} (\frac{P_{\scriptscriptstyle \, e}^*}{P_{\scriptscriptstyle \, w}^*}) P_{\scriptscriptstyle \, v,\, \infty}}{P_{\scriptscriptstyle \, e}^*}], \label{eq:Am}$$

$$B_{m} = \frac{-\mathcal{M}}{Pr Re^{1/8}} (\frac{\rho_{\infty}}{\rho_{l}}) \left(\frac{Pr}{Sc}\right)^{\frac{2}{3}} \left(\frac{\mathbf{M}_{w}}{\mathbf{M}_{a}}\right) \left[\frac{17.15 P_{v,s} \Delta T}{P_{e}^{*} (T_{m} - 38.25)}\right],$$

with

$$\begin{split} \overline{\mathbf{c}}_1 &= \frac{\mathrm{e}^{\mathrm{i}\pi/6} \, k^{1/3} \, |\mathbf{k}| \, \mathrm{Ue}^2}{\lambda^{2/3} \, \mathrm{Ai}'(0)}, \qquad \hat{\mathbf{P}} &= |\mathbf{k}| \, \mathrm{Ue}^2, \\ \overline{\alpha} &= (\mathrm{q}/\lambda) \, \frac{\mathrm{e}^{\mathrm{i}\pi/6} \, k^{1/3} \, |\mathbf{k}| \, \mathrm{Ue}^2}{\lambda^{2/3}} \end{split}$$

and

$$\overline{\theta} = (k\lambda)^{1/3} e^{i\pi/6}, \quad \overline{\overline{\theta}} = (k\lambda Pr)^{1/3} e^{i\pi/6}.$$

It is noted that, in the above expressions, Ai denotes the Airy function of the first kind. Two special functions, L_i and L_k , are introduced and they satisfy

$$L_{j}^{''} - \xi L_{j} = -1, L_{j}(\infty) = L_{j}(\infty) = 0,$$

$$L_{k}^{"} - \xi L_{k} = Ai'(Pr^{-\frac{1}{3}}\xi), L_{k}(\infty) = L_{k}'(\infty) = 0.$$

Their numerical solutions at ξ =0 are given as follows:

$$L_{j}(0) = 0.643949, \quad L_{j}'(0) = 0.469446,$$

 $L_{k}(0) = 0, \quad L_{k}'(0) = 0.169538,$

along with

$$Ai(0) = 0.35502$$
, $Ai'(0) = -0.25881$.

A number of parametric studies, based on the test condition given for Fig. 2, are performed to assess the cross flow effects, i.e. via varying W_e and λ_Z , on instability. Several important findings are obtained from the results:

- (1) There are two types of instabilities, wave–like (ω_1) and broad–band (ω_2) modes, both present in the flowfield(see Fig. 5).
- (2) The most linearly unstable modes are strictly *three-dimensional* when the cross flow is present (see Fig. 6).
- (3) The instabilities are enhanced with increasing growth rates and wave speeds as the cross flow becomes stronger, see Fig. 7.
- (4) There is a considerable change in the most observable instability growing patterns, in terms of

the characteristic length scales, when the cross flow is non–zero, see Figs. 8 and 9.

Comparison with Experiments

As mentioned early in the introduction, this study was partly motivated by the aim to understand the glaze ice roughness formation process on swept wings. To apply the stability analysis, i.e. eqn. (17), to the experimental data of Fig.3, a "quasi 3D" synthetic global flow profile was constructed for points along a given chordwise cross section (i.e. a NACA 0012 airfoil) of a swept wing, see Fig. 10. The combined 3D flow mainly contains a 2D boundary layer solution for flow past the parabolic leading edge of a NACA 0012 airfoil at zero angle of attack with some prescribed spanwise velocity distributions.

Two important observations are noticed from the stability analysis. They are summarized briefly as follows:

- (1) The leading edge region is covered entirely with three—dimensional ice roughness elements of different sizes and aspect ratios, see Fig. 11. The "average" characteristic length of the 3D roughness is about 1 mm. The smooth zone observed in Ref. 7 (see Fig. 2) for zero sweep angle condition has disappeared.
- (2) There is a narrow region of strong instability centered at some distance (\sim 8mm) downstream of the nose, see Fig. 12. The roughness elements in this zone are expected to grow much faster and larger than roughness elements in other locations. In comparison with our prediction, the critical distance (measured from the attachment line to the beginning of larger glaze ice feather zone) given by Vargas *et. al.* in Ref. 1 is about 6 mm after 1 min of ice accretion.

Connection with the Freezing Fraction

In icing scaling, the freezing fraction parameter n, derived from the Messinger energy–balance analysis for freezing at an unheated surface, can be written in the form^{13–14},

$$n = \frac{c_{p,l}}{H_{s,l}} \left(\phi + \frac{\theta}{\mathbf{b}} \right). \tag{18}$$

The terms involved are ϕ , the water droplet energy transfer parameter; θ , the air energy transfer parameter; and \mathbf{b} , the relative heat factor which was first

introduced by Tribus *et. al.*¹⁵ The analytical forms of these terms are not presented here. Interested readers are referred to Refs. 13 and 14. For more recent information, readers are referred to Ref. 16 as well.

Since Messinger's energy-balance analysis does not consider heat loss from water runback or to conduction into the cold wall, ice substrate and water film, the freezing fraction parameter is effectively related to the overall heat transfer parameter of air/droplet mixture, $q\Theta$, of the current model. After some working, the freezing fraction can be rewritten as

$$n = (S_0 Pr)^{-1} \left(\frac{\alpha_l k_{\infty}}{\alpha_{\infty} k_l} \right) \left(\frac{c_{p,l}}{c_{p,s}} \right) \left(\frac{-q\Theta}{v_{imp,0}} \right). \quad (19)$$

A numerical verification of eqn. (19) is carried out by comparing the calculated freezing fraction values at the stagnation point for (laminar) flow over a NACA 0012 airfoil against values given by Refs. 17 and 18 using eqn. (18). The results, given in Fig. 13, show good agreement consistent over all test conditions.

With this new form for $q\Theta$, the large scale ice substrate growth rate at a given location on the surface can be rewritten as (see Ref. 5 for derivation)

$$\Pr S_{0} \left(\frac{\alpha_{\infty}}{\alpha_{s}} \right) \frac{\partial \delta_{0}}{\partial t}$$

$$= \frac{\Pi}{t^{1/2}} + \left(\frac{k_{l} \alpha_{\infty}}{k_{s} \alpha_{l}} \right) \left(\frac{c_{p,s}}{c_{p,l}} \right) \left(S_{0} \Pr v_{imp,0} \right) n$$
(20)

where

$$\Pi = Re^{\frac{11}{16}} \mathcal{M}^{\frac{1}{2}} \left(\frac{\sigma}{\overline{\beta}} \right) \frac{Pr S_0 \alpha_{\infty}}{\sqrt{\pi \alpha_s L_{ref} U_{\infty}}}$$

provided that

$$\begin{split} \overline{\beta} &= H_{sl}/c_{p,s} \left(T_m \!\!-\! T_w(s) \right) \gg 1; \\ \sigma &= \left(\varrho_w \, c_{p,w} \, k_w / \varrho_s \, c_{p,s} \, k_s \right)^{1/2} \ll \overline{\beta}. \end{split}$$

The first term on the r.h.s. of eqn. (20) is the transient growth from the cold wall, and the second term is the steady-state growth rate, i.e. as $t \to \infty$. This suggests that the Messinger model really is a large time asymptote of the current model. Also the dispersion relation of eqn. (17) can be approximated as

$$\omega_1 \sim -\frac{e_1}{\beta}, \Rightarrow (\lambda, Ue) \leftrightarrow \tilde{T}$$

$$\omega_2 \sim \, - \, \frac{\Lambda}{\gamma L_0}, \quad \Rightarrow \ \, (q\Theta) \Leftrightarrow \Gamma$$

via an order of magnitude analysis of the equation. With this expression for ω_2 , the freezing fraction is directly tied to the broad-band icing mode. Furthermore, by setting $\omega_2 = 0$, the neutral stability wave number k_2 is found to be

$$k_2 \; = \; \sqrt{\left(\frac{n}{\mathcal{M}_{\text{D}}}\right)\!\!\left(\!\frac{\rho_{\textit{l}}}{\rho_{\text{S}}}\!\right)\!\!\left(\!\frac{\alpha_{\,\text{m}}}{\alpha_{\textit{l}}}\right)\!\!\left(\!\frac{c_{\,\text{p,S}}}{c_{\,\text{p,l}}}\!\right)\!\operatorname{Pr} v_{\text{imp,0}}\!\!\left(\!\frac{\operatorname{Re}^{\,-1/2}L_{\text{ref}}}{d_{\,0}}\!\right)}$$

which gives

$$\lambda_2 \sim \sqrt{\frac{L_{\text{ref}} d_0}{n}} \sim O(\mu m)$$

the smallest unstable ice roughness a physical length scale that is close to an ice feather. In summary, the freezing fraction is found to be an important parameter that can control small scale ice roughness (feather) growth.

Conclusions

A three–dimensional triple–deck local flow structure is developed to study the impact of large–scale cross flow on the creation of ice roughness elements on the leading edge of a swept wing under glaze icing conditions. A linear stability analysis is performed locally and found that when the cross flow is present, the instabilities enhance and the most linearly unstable growing ice roughness are fully three dimensional.

For glaze icing conditions tested on a NACA 0012 swept wing^{1–4}, two important observations are obtained from the stability analysis. First of all, the leading edge region is covered entirely with 3D ice roughness of mm size. The smooth zone, observed and reported by Anderson ⁷, has disappeared. Secondly, there is a narrow region of strong instability located at about 8 mm away from the nose. The roughness elements in this zone are expected to grow much faster and larger than roughness elements in other locations. In comparison with our prediction, the critical distance (measured from the attachment line to the beginning of larger glaze ice feather zone) given by Vargas *et. al.* in Ref. 1 is about 6 mm after 1 min of ice accretion.

A connection between the Messinger freezing fraction and the current glaze icing model has been established. This parameter is found to be important for small scale ice roughness (ice feather) growth.

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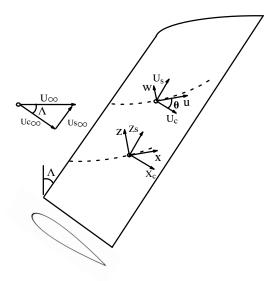


Figure 1: Schematic diagram of the flow geometry and the associated Cartesian coordinate system in which the y-direction is out of the plane. The broken lines represent the surface streamlines.



Figure 2: A close–up front view of the leading edge of a wing section, at zero sweep angle, after 1 min of ice accretion showing a smooth zone centered at the stagnation line and surrounding rough zones with roughness elements of mm size. 6–10–96 Run 6 with n=0.41, taken from Ref. 7.

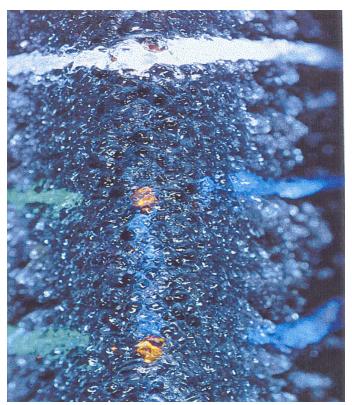


Figure 3: A close–up view of the leading edge of a wing section, at 45⁰ sweep angle, after 1 min of ice accretion showing roughness elements of mm size covering the entire leading edge region. 6–18–96 Run 3 with n=0.43, taken from Ref. 1.

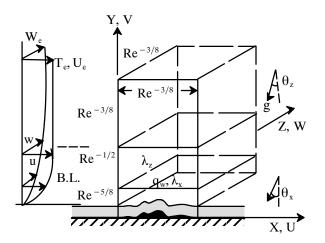


Figure 4: Schematic diagram of the local 3D triple–deck structure with an oncoming steady3D boundary layer base flow. The (θ_X, θ_Z) are the surface inclination angles w.r.t. the horizon at a given point along the X and Z directions.

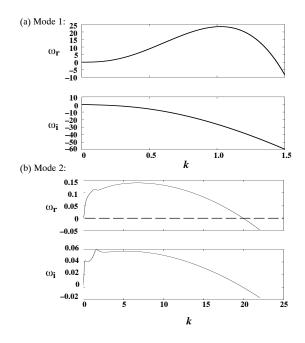


Figure 5: Typical wavelike (mode 1) and broadband (mode 2) instability modes for a linearly unstable case.

(2)	FH(mm) 0.0022 0.0170 0.0220 0.0500 0.2200	kx1 2.1000 1.2600 1.2000 1.0800 0.9900	Dx1(mm) 0.460249 0.767081 0.805435 0.894928 0.976285	kz1 0.0000 0.0000 0.0000 0.0000 0.0000	Dz1(mm) Inf Inf Inf Inf Inf Inf
(a)	FH(mm) 0.0022 0.0170	kx2 4.6000 1.7500	Dx2(mm) 0.210113 0.552298	kz2 0.0000 0.0000	Dz2(mm) Inf Inf
	0.0220 0.0500 0.2200	1.6000 17.000 12.450	0.604076 0.056854 0.077632	0.0000 0.0000 0.0000	Inf Inf Inf
1					
	FH(mm)	kx1	Dx1(mm)	kz1	Dz1(mm)
	0.0022	1.8000	0.536957	1.8000	0.536957
	0.0170	1.1000	0.878656	1.1300	0.855329
	0.0220 0.0500	1.0600 0.9700	0.911813	1.0800	0.894928 0.966522
	0.0300	0.9700	0.996414 1.062112	0.9300	1.039271
<i>a</i> \					1.00,2,1
(b)					
(b)	FH(mm)	kx2	Dx2(mm)	kz2	Dz2(mm)
(b)	0.0022	3.6000	0.268478	3.7000	Dz2(mm) 0.261222
(b)	0.0022 0.0170	3.6000 1.4500	0.268478 0.666567	3.7000 1.5000	Dz2(mm) 0.261222 0.644348
(b)	0.0022 0.0170 0.0220	3.6000 1.4500 1.3700	0.268478 0.666567 0.705490	3.7000 1.5000 1.4300	Dz2(mm) 0.261222 0.644348 0.675889
(b)	0.0022 0.0170	3.6000 1.4500	0.268478 0.666567	3.7000 1.5000	Dz2(mm) 0.261222 0.644348

Figure 6: The most linearly unstable modes at different water film thickness values for (a) zero cross flow (b) non–zero cross flow (W_e =0.7, λ_Z =0.5) conditions.

	0.0220 0.0500	2.1000 1.2400 1.1900 1.0700	0.4500 0.3000 0.2900 0.2700	ω _{r_} abs1 8.938866e- 3.899485e- 6.814523e- 4.712507e+ 544874e+0	003 -2.406 001 -1.590 001 -2.2118 000 -7.955	989e-001 248e+000 390e+000 895e+000
(a)						
	FH(mm)	kx2	kz2	ω _{r_} abs2	ω _{i_} al	os2
	0.0022	4.4500	1.1400	7.831821e-	-005 5.8391	13e-005
	0.0170	1.6500	0.5300	3.816821e-	-005 2.2384	19e–005
	0.0220	1.5500		3.406755e-		. ,
	0.0500	16.650		2.234151e-		,
	0.2200	12.200	2.4500	1.170113e-	005 2.0901	18e–006
	FH(mm)		kz1		ω _{i_al}	
	0.0022	1.800		.854233e-0		
	0.0170	1.100		0.579297e-0		
	0.0220	1.060		.723385e+0		,
	0.0500 0.2200	0.970 0.910		.300116e+0 7.733908e+0		
(b)	0.2200	0.910	0.930 /	1.7339086+0	02 -/.1/41	436+002
(0)						
	FH(mm)			ω_{r} abs2		
	0.0022	3.600		0.182444e=0		
	0.0170	1.450		.425115e-0		
	0.0220	1.370		3.893367e-0		
	0.0500	1.260		2.415656e-0		
	0.2200	8.450	8.600 1	1.215725e-0	05 2.05018	4e–006

Figure 7:The most linearly unstable modes at different water film thickness for (a) smaller cross flow (W_e =0.26, λ_Z =0.1)(b) larger cross flow (W_e =0.7, λ_Z =0.5) conditions.

(a)	FH(mm)	kx1	Dx1(mm)	kz1	Dz1(mm)
	0.0022	2.100	0.460249	0.450	2.147827
	0.0170	1.240	0.779453	0.300	3.221740
	0.0220	1.190	0.812203	0.290	3.332834
	0.0500	1.070	0.903292	0.270	3.579711
	0.2200	0.980	0.986247	0.260	3.717392
(b)	FH(mm)	kx1	Dx1(mm)	kz1	Dz1(mm)
	0.0022	2.400	0.402717	1.950	0.495652
	0.0170	1.550	0.623563	0.920	1.050567
	0.0220	1.470	0.657498	0.860	1.123863
	0.0500	1.330	0.726708	0.740	1.306111
	0.2200	1.230	0.785790	0.650	1.486957
(c)	FH(mm)	kx1	Dx1(mm)	kz1	Dz1(mm)
	0.0022	0.760	1.271739	7.650	0.126343
	0.0170	0.570	1.695653	5.700	0.169565
	0.0220	0.560	1.725932	5.600	0.172593
	0.0500	0.540	1.789856	5.400	0.178986
	0.2200	0.530	1.823626	5.300	0.182363

Figure 8: The most linearly unstable wave–like mode at different film thickness for (a)W_e=0.26, λ_Z =0.1(b) W_e=0, λ_Z =1.0 (c)W_e=5.0, λ_Z =5.0 conditions.

(a)	FH(mm)	kx2	Dx2(mm)	kz2	Dz2(mm)
	0.0022	4.4500	0.217196	1.1400	0.847826
	0.0170	1.6500	0.585771	0.5300	1.823626
	0.0220	1.5500	0.623563	0.4700	2.056430
	0.0500	16.650	0.058049	3.3500	0.288514
	0.2200	12.200	0.079223	2.4500	0.394499
(b)	FH(mm)	kx2	Dx2(mm)	kz2	Dz2(mm)
	0.0022	5.3500	0.180658	2.7000	0.357971
	0.0170	2.1000	0.460249	0.6600	1.464427
	0.0220	1.9500	0.495652	0.6400	1.510191
	0.0500	7.3500	0.131500	14.850	0.065086
	0.2200	5.1500	0.187674	10.350	0.093384
(c)	FH(mm)	kx2	Dx2(mm)	kz2	Dz2(mm)
	0.0022	1.1300	0.855329	11.100	0.087074
	0.0170	0.7300	1.324003	7.7500	0.124713
	0.0220	0.7900	1.223446	7.7000	0.125522
	0.0500	0.7900	1.223446	7.8500	0.123124
	0.2200	0.8300	1.164484	8.4500	0.114381

Figure 9: The most linearly unstable broad–band-mode at different film thickness for (a)W_e=0.26, λ_Z =0.1(b) W_e=0, λ_Z =1.0 (c)W_e=5.0, λ_Z =5.0 conditions.

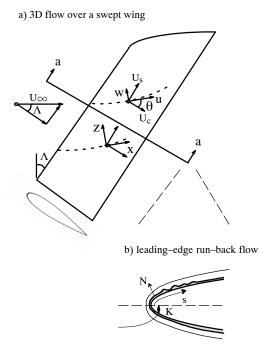


Figure 10: Schematic diagram for the synthesis of the "quasi 3D" flow over a NACA 0012 swept wing. The synthetic flow profile at a given cross section (i.e. line aa) mainly contains a 2D BL flow over a NACA 0012 airfoil with some prescribed spanwise velocity distributions.

_					
	FH(mm)	kx1	Dx1(mm)	kz1	Dz1(mm)
	0.0022	0.8800	1.098320	0.7500	1.288696
(a)	0.0170	0.4500	2.147827	0.4500	2.147827
(4)	0.0220	0.4200	2.301243	0.4300	2.247726
	0.0500	0.3600	2.684783	0.3800	2.543479
	0.2200	0.3000	3.221740	0.3400	2.842712
ſ	FH(mm)	kx1	Dx1(mm)	kz1	Dz1(mm)
	0.0022	1.7500	0.552298	1.3100	0.737803
(h)	0.0170	1.0100	0.956952	0.8300	1.164484
(b)	0.0220	0.9700	0.996414	0.8000	1.208152
	0.0500	0.8600	1.123863	0.7400	1.306111
	0.2200	0.7900	1.223446	0.6900	1.400756
	FH(mm)	kx1	Dx1(mm)	kz1	Dz1(mm)
	0.0022	1.8000	0.536957	1.8000	0.536957
(c)	0.0170	1.1000	0.878656	1.1300	0.855329
	0.0220	1.0600	0.911813	1.0800	0.894928
	0.0500	0.9700	0.996414	1.0000	0.966522
	0.2200	0.9100	1.062112	0.9300	1.039271
	FH(mm)	kx1	Dx1(mm)	kz1	Dz1(mm)
	0.0022	1.8000	0.536957	1.2500	0.773218
(4)	0.0170	1.0700	0.903292	0.7600	1.271739
(d)	0.0220	1.0200	0.947571	0.7400	1.306111
	0.0500	0.9300	1.039271	0.6700	1.442570
	0.2200	0.8600	1.123863	0.6300	1.534162

Figure 11:The most linearly unstable ice roughness elements at various chordwise (s^*) locations (a) s^* =0.1mm, (b) s^* =4 mm, (c) s^* =8 mm, and (d) s^* =12.6 mm with different film thickness.

(a)	0.0170 0 0.0220 0 0.0500 0	0.4500 0.4200 0.3600	0.4500 2 0.4300 4 0.3800 2	7.900497e-004 2.871825e-002 4.799280e-002 2.848893e-001	WI_abs1 -3.913777e-002 -2.055635e-001 -2.686901e-001 -7.638027e-001 -1.380330e+001
(b)	0.0022 1 0.0170 1 0.0220 0 0.0500 0	.0100 0.9700 0.8600	0.8300 4 0.8000 7 0.7400 5	4.523393e-001 7.967976e-001 5.644905e+000	WI_abs1 -2.570365e-001 -1.757830e+000 -2.472327e+000 -9.263617e+000 -2.886595e+002
(c)	0.0022 1 0.0170 1 0.0220 1 0.0500 0	.1000 .0600 .9700	1.8000 1.1300 1.0800 1.0000	9.579297e-001 1.723385e+000 1.300116e+001	WI_abs1 -4.062437e-001 -3.177195e+000 -4.570972e+000 -1.955354e+001 -7.174143e+002
(d)	0.0170 1 0.0220 1 0.0500 0	kx1 1.8000 1.0700 1.0200 0.9300 0.8600	0.7600 0.7400 0.6700	5.002525e-001 8.927919e-001 6.572208e+000	WI_abs1 -2.583472e-001 -1.882614e+000 -2.688304e+000 -1.090498e+001 2-3.778358e+002

Figure 12: The growth rates of most linearly unstable ice roughness elements at various chordwise (s*) locations (a) s*=0.1mm, (b) s*=4 mm, (c) s*=8 mm, and (d) s*=12.6 mm with different film thickness.

(1) Conditions from Ref. 17

Test Date	c (cm)	Run	T _∞ (°C)	V∞ (m/s)	LWC g/m ³	n eqn. (18)	n eqn. (19)
3–21–01	53.3	4	-26.1	66.8	1.00	1.00	1.00
3–9–01	91.4	1	-15.7	77.5	0.68	0.60	0.56
3–19–01	53.3	9	-16.8	126.2	0.56	0.60	0.51
3-20-01	53.3	4	-16.3	109.2	0.67	0.60	0.53

(2) Conditions from Ref. 18

Test Date	c (cm)	Run	T _∞ (°C)	V∞ (m/s)	LWC g/m ³	n eqn. (18)	n eqn. (19)
11–13–00	53.3	7	-19	67	0.99	0.77	0.73
3-19-01	53.3	6	-10	67	1.00	0.40	0.37
3–20–01	53.3	1	-7	67	1.00	0.28	0.26
11–13–00	53.3	8	-27	67	0.99	1.00	1.00

Figure 13: Test conditions and results for comparing the freezing fraction calculation obtained from eqn. $(18)^{17-18}$ and eqn. (19).

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